

#6

Goldstein 12.11

Get Lagrangian / Hamiltonian

$$y = (l - l \cos \theta) \sin \alpha, \quad x = (l - l \sin \theta) \cos \alpha$$

$$U = mgy = mgl(1 - \cos \theta) \sin \alpha$$

when  $\theta$  is small, <sup>(which it is)</sup>  $\cos \theta \approx 1 - \frac{\theta^2}{2} \Rightarrow U \approx \frac{mgl}{2} \theta^2 \sin \alpha$

$$T = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2) \approx \frac{1}{2} m l^2 \dot{\theta}^2$$

$$L = \frac{1}{2} m l^2 \dot{\theta}^2 - \frac{mgl}{2} \theta^2 \sin \alpha$$

Euler Lagrange equations:

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0 = m l^2 \ddot{\theta} + mgl \theta \sin \alpha \Rightarrow \ddot{\theta} + \left( \frac{g}{l} \sin \alpha \right) \theta = 0$$

$$\textcircled{1} \Rightarrow \theta = A \cos \left( \sqrt{\frac{g}{l} \sin \alpha} t \right) + B \sin \left( \sqrt{\frac{g}{l} \sin \alpha} t \right)$$

Also,  $P = \frac{\partial L}{\partial \dot{\theta}} = m l^2 \dot{\theta}$ , so  $H = m l^2 \dot{\theta}^2 - \frac{1}{2} m l^2 \dot{\theta}^2 + \frac{mgl}{2} \theta^2 \sin \alpha$

$$H = \frac{1}{2} m l^2 \dot{\theta}^2 + \frac{mgl}{2} \theta^2 \sin \alpha = \frac{P^2}{2m l^2} + \frac{mgl}{2} \theta^2 \sin \alpha = E \quad \textcircled{2}$$

Transform to Action/Angle Variables.

$$J = \oint p dq \quad \text{From the Hamiltonian, } p^2 = 2m l^2 E - m^2 l^3 g \theta^2 \sin \alpha$$

$$\text{so } J = \oint \sqrt{2m l^2 E - m^2 l^3 g \theta^2 \sin \alpha} d\theta$$

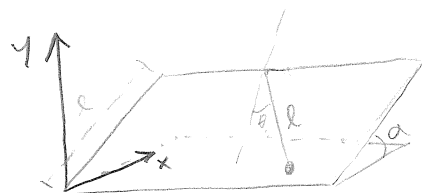
$$J = \sqrt{2m l^2 E} \oint \sqrt{1 - \frac{m l g \sin \alpha}{2E} \theta^2} d\theta$$

use  $\phi = \sqrt{\frac{2E}{mgl \sin \alpha}} \theta \Rightarrow d\theta = \sqrt{\frac{2E}{mgl \sin \alpha}} \cos \phi d\phi$

$$\therefore J = \sqrt{2m l^2 E} \sqrt{\frac{2E}{mgl \sin \alpha}} \int_0^{2\pi} \cos^2 \phi d\phi = 2\pi E \sqrt{\frac{l}{g \sin \alpha}}$$

Rewrite Hamiltonian, in terms of J

$$E = \frac{J}{2\pi} \sqrt{\frac{g \sin \alpha}{l}} \Rightarrow H = \frac{J}{2\pi} \sqrt{\frac{g \sin \alpha}{l}}$$



Now, notice from ~~①~~,  $A = \theta_{\max}$ . (A is the amplitude)

So, what is  $\theta_{\max}$ ? It is easy to see by plotting ② in phase space:

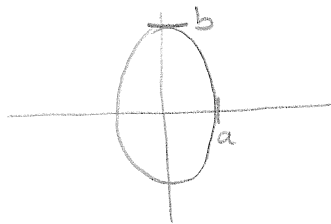
$$1 = \frac{p^2}{2ml^2E} + \frac{\theta^2}{\frac{2E}{mgl\sin\alpha}}$$

(rearranging to look like an ellipse where we have

$$1 = \left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^2$$

Thus the semi-major and semi-minor axes (a and b) are given by

$$a = \sqrt{2ml^2E}, \quad b = \sqrt{\frac{2E}{mgl\sin\alpha}}$$



Then it's easy to see that  $b = \theta_{\max} = \sqrt{\frac{2E}{mgl\sin\alpha}}$

$$\text{Thus } A = \sqrt{\frac{2E}{mgl\sin\alpha}} = \sqrt{\frac{2}{mgl\sin\alpha}} \sqrt{\frac{J}{2\pi}} \sqrt{\frac{g\sin\alpha}{l}}$$

$$A = \sqrt{\frac{J}{ml^{3/2} \sqrt{g\sin\alpha} \pi}} = \sqrt{\frac{J}{ml^{3/2} g^{1/2}} (\sin\alpha)^{-1/4}}$$

Noting finally that this motion is adiabatic, so  $J = \text{constant}$ ,  
The amplitude varies as a function of  $(\sin\alpha)^{-1/4}$