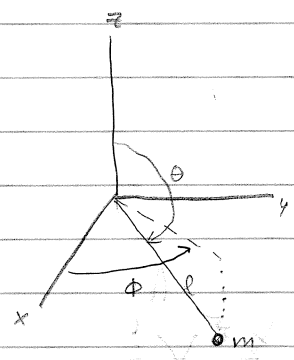


1-19

Here we have the 3-D simple pendulum w/ mass m , and massless/thin, rigid string l .

in cartesian: $T = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2 + \dot{z}^2)$, $U = mgz$

We used θ and ϕ as gen. coordinates as defined in diagram \rightarrow



$$\begin{aligned} x &= l \sin \theta \cos \phi & \rightarrow & \dot{x} = -l \sin \theta \dot{\phi} \sin \phi + l \dot{\theta} \cos \theta \cos \phi \\ y &= l \sin \theta \sin \phi & \rightarrow & \dot{y} = -l \sin \theta \dot{\phi} \cos \phi + l \dot{\theta} \cos \theta \sin \phi \\ z &= l \cos \theta & \rightarrow & \dot{z} = -l \dot{\theta} \sin \theta \end{aligned}$$

Plug these into T :

$$\begin{aligned} T &= \frac{1}{2}m [l^2 \sin^2 \theta \sin^2 \phi (\dot{\phi}^2) + l^2 (\dot{\theta}^2) \cos^2 \theta \cos^2 \phi - 2l^2 \sin \theta \cos \theta \sin \phi \cos \phi (\dot{\phi})(\dot{\theta}) \\ &\quad + l^2 \sin^2 \theta \cos^2 \phi (\dot{\phi}^2) + l^2 \cos^2 \theta \sin^2 \phi (\dot{\theta}^2) + 2l^2 \sin \theta \cos \theta \sin \phi \cos \phi (\dot{\phi})(\dot{\theta}) \\ &\quad + l^2 \sin^2 \theta (\dot{\theta}^2)] \\ &= \frac{1}{2}ml^2 [(\dot{\phi}^2) [\sin^2 \theta \sin^2 \phi + \sin^2 \theta \cos^2 \phi] + (\dot{\theta}^2) [\cos^2 \theta \cos^2 \phi + \cos^2 \theta \sin^2 \phi + \sin^2 \theta]] \\ &= \frac{1}{2}ml^2 [\dot{\phi}^2 \sin^2 \theta + \dot{\theta}^2 (\cos^2 \theta + \sin^2 \theta)] = \left(\frac{1}{2}ml^2 [\dot{\phi}^2 \sin^2 \theta + \dot{\theta}^2] \right) \checkmark \end{aligned}$$

also, $U = mgz = mgl \cos \theta$ \checkmark

1-19 continued

$$L = T - U = \frac{1}{2}ml^2(\dot{\phi}^2 \sin^2 \theta + \dot{\theta}^2) - mgl \cos \theta$$

Now, we apply the Euler-Lagrange equations. First for θ :

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0$$

$$\frac{d}{dt} [ml^2 \dot{\theta}] - [mgl \sin \theta + \frac{1}{2}ml^2 \dot{\phi}^2 \sin(2\theta)] = 0$$

$$\boxed{\ddot{\theta} = \frac{g}{l} \sin \theta + \dot{\phi}^2 \sin \theta \cos \theta} \checkmark$$

And now for ϕ :

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\phi}} \right) - \frac{\partial L}{\partial \phi} = 0 \Rightarrow \frac{d}{dt} [ml^2 \dot{\phi} \sin^2 \theta] = 0$$

$$ml^2 \ddot{\phi} \sin^2 \theta + 2ml^2 \dot{\phi} \sin \theta \cos \theta \dot{\theta} = 0$$

$$\ddot{\phi} \sin^2 \theta + 2\dot{\phi} \sin \theta \cos \theta \dot{\theta} = 0 \Rightarrow \boxed{\ddot{\phi} = -2\dot{\phi} \cot \theta} \checkmark$$

The boxed quantities are the equations of motion.

what can you say about this quantity? what is it physically?

no physical discussion

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