

(a) Start off with a generic state for a spin state:

Sakurai 3-10

$$|\alpha\rangle = \cos(\frac{\theta}{2})|+\rangle + e^{i\phi} \sin(\frac{\theta}{2})|-\rangle$$

where $\phi \in [-\pi, \pi]$ is the relative phase, and $\cos(\frac{\theta}{2}), \sin(\frac{\theta}{2}) \in \mathbb{R}^+$ (we can ignore overall phase).

I will write the (known) expectation values in terms of ϕ and θ . Then I will solve for the unknowns.

$$\begin{aligned} \rightarrow \langle S_x \rangle &= \langle \alpha | S_x | \alpha \rangle = \frac{\hbar}{2} \langle \alpha | (|+\rangle\langle -| + |-\rangle\langle +|) | \alpha \rangle \quad \text{by 3.21} \\ &= \frac{\hbar}{2} \langle \alpha | + \rangle \langle - | \alpha \rangle + \frac{\hbar}{2} \langle \alpha | - \rangle \langle + | \alpha \rangle \\ &= \frac{\hbar}{2} \cos(\frac{\theta}{2}) e^{i\phi} \sin(\frac{\theta}{2}) + \frac{\hbar}{2} e^{-i\phi} \sin(\frac{\theta}{2}) \cos(\frac{\theta}{2}) = \frac{\hbar}{2} \cos(\frac{\theta}{2}) \sin(\frac{\theta}{2}) \left[\frac{e^{i\phi} + e^{-i\phi}}{2} \right] \\ &= \frac{\hbar}{2} \cos(\frac{\theta}{2}) \sin(\frac{\theta}{2}) \cos(\phi) = \frac{\hbar}{2} \sin(\theta) \cos(\phi) \quad \textcircled{1} \checkmark \end{aligned}$$

$$\begin{aligned} \rightarrow \langle S_y \rangle &= \langle \alpha | S_y | \alpha \rangle = -\frac{i\hbar}{2} \langle \alpha | + \rangle \langle - | \alpha \rangle + \frac{i\hbar}{2} \langle \alpha | - \rangle \langle + | \alpha \rangle \quad \text{similarly} \\ &= -\frac{i\hbar}{2} \cos(\frac{\theta}{2}) e^{i\phi} \sin(\frac{\theta}{2}) + \frac{i\hbar}{2} e^{-i\phi} \sin(\frac{\theta}{2}) \cos(\frac{\theta}{2}) \\ &= \frac{\hbar}{2} \cos(\frac{\theta}{2}) \sin(\frac{\theta}{2}) \sin(\phi) \Rightarrow \langle S_y \rangle = \frac{\hbar}{2} \sin(\theta) \sin(\phi) \quad \textcircled{2} \checkmark \end{aligned}$$

$$\begin{aligned} \rightarrow \langle S_z \rangle &= \langle \alpha | S_z | \alpha \rangle = \frac{\hbar}{2} \langle \alpha | + \rangle \langle + | \alpha \rangle - \frac{\hbar}{2} \langle \alpha | - \rangle \langle - | \alpha \rangle \\ &= \frac{\hbar}{2} (\cos^2(\frac{\theta}{2}) - \sin^2(\frac{\theta}{2})) = \frac{\hbar}{2} \cos(\theta) \quad \textcircled{3} \checkmark \end{aligned}$$

Of course, we remember that $\langle S_x \rangle, \langle S_z \rangle$ are known, while $\langle S_y \rangle$ is not except for its sign.

\rightarrow by $\textcircled{3}$, $\theta = \cos^{-1}(\frac{2}{\hbar} \langle S_z \rangle)$, where we can be sure θ is positive, since $\sin(\frac{\theta}{2}) \in \mathbb{R}^+$. Great! we know $\sin(\frac{\theta}{2})$ and $\cos(\frac{\theta}{2})$.

\rightarrow Plugging that into $\textcircled{1}$, we get $\cos \phi = \frac{2 \langle S_x \rangle}{\hbar \sin \theta}$ (where $\frac{2 \langle S_x \rangle}{\hbar \sin \theta}$ is now a known constant).

BUT!! $\phi = \pm \cos^{-1}(\frac{2 \langle S_x \rangle}{\hbar \sin \theta})$ since \cos is even.

How can we find the sign of ϕ ?

\rightarrow equation $\textcircled{2}$ to the rescue. This gives $\sin \phi = \frac{2 \langle S_y \rangle}{\hbar \sin \theta}$. $\frac{2}{\hbar \sin \theta}$ is a positive constant, so the sign of $\langle S_y \rangle$ gives the sign of $\sin \phi$, and hence the sign of ϕ .

Note the magnitude of ϕ can be found using just $\langle S_x \rangle$ and $\langle S_z \rangle$, but we still do need the sign of $\langle S_y \rangle$ to get the sign of ϕ .

(b) we'll use a general matrix $\rho = \begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix}$, and use $[S_x], [S_y], [S_z]$ to determine

the unknown greek letters in our $\text{pin}^{-1/2}$ density matrix

Using $[A] = \text{tr}(\rho A)$, and $S_x = \frac{\hbar}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$, $S_y = \frac{\hbar}{2} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$, $S_z = \frac{\hbar}{2} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$

$$\text{Thus, } [S_x] = \text{tr}(\rho S_x) = \text{tr} \left(\begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix} \frac{\hbar}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right) = \frac{\hbar}{2} \text{tr} \begin{bmatrix} \beta & \alpha \\ \gamma & \delta \end{bmatrix} = \frac{\hbar}{2} (\beta + \gamma)$$

$$\text{Similarly } [S_y] = \frac{i\hbar}{2} (\beta - \gamma), \quad [S_z] = \frac{\hbar}{2} (\alpha - \delta)$$

Also, by 4.11, $\text{tr}(\rho) = 1$, so $\alpha + \delta = 1$

Thus we have enough equations to solve for α, β, γ , and δ .

Solving w/ the attached Mathematica Code:

$$\left\{ \begin{array}{l} \alpha = \frac{2[S_z] + \hbar}{2\hbar}, \quad \beta = \frac{[S_x] - i[S_y]}{\hbar} \\ \gamma = \frac{[S_x] + i[S_y]}{\hbar}, \quad \delta = \frac{-2[S_z] + \hbar}{2\hbar} \end{array} \right. \quad \checkmark \quad (10)$$

$$\text{In[515]:= Solve} \left[\left\{ \text{SX} == \frac{\hbar}{2} (\beta + \gamma), \text{SY} == \frac{i \hbar}{2} (\beta - \gamma), \text{SZ} == \frac{\hbar}{2} (\alpha - \delta), \alpha + \delta == 1 \right\}, \{\alpha, \beta, \gamma, \delta\} \right]$$

$$\text{Out[515]:=} \left\{ \left\{ \alpha \rightarrow -\frac{-2 \text{SZ} - \hbar}{2 \hbar}, \beta \rightarrow -\frac{-\text{SX} + i \text{SY}}{\hbar}, \gamma \rightarrow -\frac{-\text{SX} - i \text{SY}}{\hbar}, \delta \rightarrow -\frac{2 \text{SZ} - \hbar}{2 \hbar} \right\} \right\}$$