

Solus: 2-10

(a) given  $H = \Delta(|L\rangle\langle R| + |R\rangle\langle L|)$

Let  $|R\rangle = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $|L\rangle = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ , then  $H = \Delta \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

To find  $|v_1\rangle$  and  $|v_2\rangle$ , the eigenstates, and their eigenvalues  $\lambda_1$  and  $\lambda_2$ , just solve the usual eigenvalue problem.

$$|H - \lambda I| = 0 \Rightarrow \begin{vmatrix} -\lambda & \Delta \\ \Delta & -\lambda \end{vmatrix} = 0 \Rightarrow (\lambda^2 - \Delta^2) = 0 \Rightarrow \lambda = \pm \Delta$$

$$\lambda_1 = \Delta : (H - \Delta I)v_1 = 0 \Rightarrow \begin{bmatrix} -\Delta & \Delta \\ \Delta & -\Delta \end{bmatrix} v_1 = 0 \Rightarrow \Delta \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} = \Delta \begin{bmatrix} v_{12} - v_{11} \\ v_{11} - v_{12} \end{bmatrix} = 0$$

where  $v_i = \begin{bmatrix} v_{i1} \\ v_{i2} \end{bmatrix}$ . Thus  $v_{11} = v_{12}$  so  $v_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$$\lambda_2 = -\Delta : (H + \Delta I)v_2 = 0 \Rightarrow \Delta \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} v_2 = 0 \Rightarrow \Delta \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} v_{21} \\ v_{22} \end{bmatrix} = \Delta \begin{bmatrix} v_{21} + v_{22} \\ v_{22} + v_{21} \end{bmatrix} = 0$$

Thus  $-v_{21} = v_{22} \Rightarrow v_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

$$\begin{aligned} |v_1\rangle &= \frac{1}{\sqrt{2}} (|R\rangle + |L\rangle), \lambda_1 = \Delta \\ |v_2\rangle &= \frac{1}{\sqrt{2}} (|R\rangle - |L\rangle), \lambda_2 = -\Delta \end{aligned}$$

(b)  $U(t, t_0=0) = \exp\left[\frac{-iHt}{\hbar}\right]$

find  $|a, t_0=0, t\rangle = \exp\left(\frac{-iHt}{\hbar}\right)|a\rangle = \exp\left(\frac{-iHt}{\hbar}\right)(a_1|v_1\rangle + a_2|v_2\rangle)$

When we've used  $a_1|v_1\rangle + a_2|v_2\rangle$  as a generic state in a basis of eigenstates of  $H$ . (It helped me to keep track of constants  $a_1$  and  $a_2$  by projecting the state ket back into  $|R\rangle$  and  $|L\rangle$ , but it's not necessary)

$$|a, t_0=0, t\rangle = \frac{a_1}{\sqrt{2}} \exp\left[\frac{-i\Delta t}{\hbar}\right] (|R\rangle + |L\rangle) + \frac{a_2}{\sqrt{2}} \exp\left[\frac{i\Delta t}{\hbar}\right] (|R\rangle - |L\rangle)$$

(c) Now, if  $|a\rangle = |R\rangle$ , we need to find  $|\langle L|R(t)\rangle|^2 = \langle L|R(t)\rangle^* \langle L|R(t)\rangle = \langle R(t)|L\rangle \langle L|R(t)\rangle$

Plug in  $U(t)|R\rangle = |R(t)\rangle$

$$\langle R|\exp\left[\frac{iHt}{\hbar}\right]|L\rangle \langle L|\exp\left[\frac{-iHt}{\hbar}\right]|R\rangle$$

Next, let's plug in completeness explicitly:

$$\begin{aligned} & (\langle R|v_1\rangle \langle v_1|\exp\left[\frac{iHt}{\hbar}\right]|L\rangle + \langle R|v_2\rangle \langle v_2|\exp\left[\frac{iHt}{\hbar}\right]|L\rangle) (\langle L|\exp\left[\frac{-iHt}{\hbar}\right]|v_1\rangle \langle v_1|R\rangle + \langle L|\exp\left[\frac{-iHt}{\hbar}\right]|v_2\rangle \langle v_2|R\rangle) \\ &= \frac{\exp\left[\frac{+i\Delta t}{\hbar}\right]}{2} \left[ (\langle R|R\rangle + \langle R|L\rangle)(\langle R|R\rangle + \langle L|L\rangle) + (\langle R|R\rangle - \langle R|L\rangle)(\langle R|L\rangle - \langle L|L\rangle) \right] \exp\left[\frac{-i\Delta t}{\hbar}\right] \\ & \quad \cdot \frac{\exp\left[\frac{-i\Delta t}{\hbar}\right]}{2} \left[ (\langle L|R\rangle + \langle L|L\rangle)(\langle R|R\rangle + \langle L|R\rangle) + (\langle L|R\rangle - \langle L|L\rangle)(\langle R|R\rangle - \langle L|R\rangle) \right] \exp\left[\frac{i\Delta t}{\hbar}\right] \end{aligned}$$

$$= \left( \frac{1}{2} \exp\left[\frac{i\Delta t}{\hbar}\right] - \frac{1}{2} \exp\left[-\frac{i\Delta t}{\hbar}\right] \right) \left( \frac{1}{2} \exp\left[-\frac{i\Delta t}{\hbar}\right] - \frac{1}{2} \exp\left[\frac{i\Delta t}{\hbar}\right] \right)$$

$$= \frac{1}{4} + \frac{1}{4} - \frac{1}{4} \exp\left[-\frac{2i\Delta t}{\hbar}\right] - \frac{1}{4} \exp\left[\frac{2i\Delta t}{\hbar}\right] = \frac{1}{2} - \frac{1}{2} \cos\left(\frac{2\Delta t}{\hbar}\right) \checkmark$$

(d) Here are the Schrödinger equations:

$$i\hbar \frac{\partial}{\partial t} \langle R | \alpha, t_0=0, t \rangle = \langle R | H | \alpha, t_0=0, t \rangle = \Delta \langle L | \alpha(t) \rangle$$

$$i\hbar \frac{\partial}{\partial t} \langle L | \alpha, t_0=0, t \rangle = \langle L | H | \alpha, t_0=0, t \rangle = \Delta \langle R | \alpha(t) \rangle$$

And differentiate again to get, for the  $|R\rangle$  equation:

$$-\hbar^2 \frac{\partial^2}{\partial x^2} \langle R | \alpha(x) \rangle = \langle R | \alpha(x) \rangle \quad \text{and the same for } |L\rangle$$

which has solutions  $\left[ a_1 \sin\left(\frac{\Delta x}{\hbar}\right) + a_2 \cos\left(\frac{\Delta x}{\hbar}\right) = \langle R | \alpha(x) \rangle = \langle L | \alpha(x) \rangle \right]$

Thus, for our arbitrary state  $|\alpha\rangle$

$$|\alpha\rangle = \frac{a_1}{\sqrt{2}} \left( \cos\left(-\frac{\Delta x}{\hbar}\right) + i \sin\left(-\frac{\Delta x}{\hbar}\right) \right) (|R\rangle + |L\rangle) + \frac{a_2}{\sqrt{2}} \left( \cos\left(\frac{\Delta x}{\hbar}\right) + i \sin\left(\frac{\Delta x}{\hbar}\right) \right) (|R\rangle - |L\rangle)$$

$$= \frac{2}{\sqrt{2}} \left[ \cos\left(\frac{\Delta x}{\hbar}\right) |R\rangle - i \sin\left(\frac{\Delta x}{\hbar}\right) |L\rangle \right] \checkmark$$

which is what you'd expect from b.

(e)  $\langle \alpha(t) | \alpha(t) \rangle = 1$  (or @ least it should!)

$$\langle \alpha(t) | \alpha(t) \rangle = \langle \alpha(0) | U^\dagger U | \alpha(0) \rangle = \langle \alpha_0 | \exp\left[\frac{iHt}{\hbar}\right] \exp\left[-\frac{iHt}{\hbar}\right] | \alpha_0 \rangle$$

and  $H^\dagger = \Delta |R\rangle\langle L| \neq H$  (i.e. it's not Hermitian!)

thus  $\exp\left[\frac{iHt}{\hbar}\right] \exp\left[-\frac{iHt}{\hbar}\right] \neq I$ , so  $\langle \alpha_0 | U^\dagger U | \alpha_0 \rangle \neq 1$

and probability isn't conserved.

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