

$\langle [x_i, G(\vec{p})] \rangle = [x_i, G(p_i)]$  because we can always consolidate the other terms ( $p_j, p_k, \dots$ ) will always come w/ $x_i$ , and those terms will go to zero.  $\rightarrow$  They'll stick around, but they will not be affected by differentiation with respect to  $x_i$ .

Sakurai 1.29

Taylor series:

$$G(p_i) = \sum_{n=0}^{\infty} g_n p_i^n \text{ to } x_i.$$

Note:

$$[A, B^n] = n B^{n-1} [A, B] \rightarrow \text{① where did this come from?}$$

(can be proved for  $x_i$  and  $p_i$  by induction)

$$\begin{aligned} [x_i, G(\vec{p})] &= [x_i, \sum_{n=0}^{\infty} g_n p_i^n] = [x_i, g_1 p_i] + [x_i, g_2 p_i^2] \\ &\quad + \sum_{n=3}^{\infty} [x_i, g_n p_i^n] \\ &= \sum_{n=0}^{\infty} g_n [x_i, p_i^n] = \underbrace{\sum_{n=0}^{\infty} g_n n p_i^{(n-1)} [x_i, p_i]}_{\text{see above identity.}} \end{aligned}$$

$$= i\hbar \sum_{n=0}^{\infty} n g_n p_i^{(n-1)} = i\hbar \frac{\partial G}{\partial p_i} \quad \square$$

$$(because \frac{\partial}{\partial p_i} G = \frac{\partial}{\partial p_i} \sum_{n=0}^{\infty} g_n p_i^n = \sum_{n=0}^{\infty} g_n n p_i^{n-1})$$

Likewise

$$\begin{aligned} [p_i, F(\vec{x})] &= [p_i, F(x_i)] = [p_i, \sum_{n=0}^{\infty} f_n x_i^n] = \sum_{n=0}^{\infty} f_n [p_i, x_i^n] = \sum_{n=0}^{\infty} f_n n x_i^{n-1} [p_i, x_i] \\ &= -i\hbar \sum_{n=0}^{\infty} f_n n x_i^{n-1} = -i\hbar \frac{\partial F}{\partial x_i} \quad \square \end{aligned}$$

as before

$$\begin{aligned} \textcircled{b} [x^2, p^2] &= [x^2, p] p + p [x^2, p] = x [x, p] p + [x, p] x p \\ &\quad + p x [x, p] + p [x, p] x \end{aligned}$$

$$= x i\hbar p + i\hbar x p + p x i\hbar + p i\hbar x$$

$$= i\hbar (2xp + 2px) = \boxed{2i\hbar (xp + px)} \quad \square$$

$$[x^2, p^2]_{\text{classical}} = \frac{\partial x^2}{\partial x} \frac{\partial p^2}{\partial p} - \frac{\partial x^2}{\partial p} \frac{\partial p^2}{\partial x} = 2x \cdot 2p = 4xp \quad \square$$

This is by 1.6.43 which states:

$$[A(q, p), B(q, p)]_{\text{classical}} = \sum_s \left( \frac{\partial A}{\partial q_s} \frac{\partial B}{\partial p_s} - \frac{\partial A}{\partial p_s} \frac{\partial B}{\partial q_s} \right)$$

(Poisson brackets! You'll encounter those in classical mechanics soon.)

where  $A \rightarrow x^2$ ,  $B \rightarrow p^2$ ,  $q \rightarrow x$ ,  $p \rightarrow p$  (duh),

and we have just one  $s$ .